Time Frequency analysis of Non-Stationary signals by Differential frequency window S – Transform

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Abstract

The S transform is an extension of Short Time Fourier Transform and Wavelet transform, has a time frequency resolution which is far from ideal. A differential frequency window is proposed in this paper to enhance the time frequency energy localization. When a non stationary signal consists of abrupt amplitude variation equal to peak of Gaussian function at initial intervals of chosen gaussian window, then some part of the signal amplitude will be nullified during transformation process. The major function of differential frequency window is to track all abrupt amplitude-frequency variations which exploits in non – stationary signals. A mathematical method namely Newton Raphson method is adopted for this trace. The proposed scheme is tested for ECG data in presence of noise environment and results shows that proposed algorithm produces better enhanced energy localization in comparison to the standard S – Transform, STFT, and CWT. Furthermore the above algorithm is implemented on FPGAs for real time applications.

Keywords: Newton Raphson method, S-Transform, Localization, ECG.

1. Introduction

Analysis of non stationary signal acquires the highest priority in many of real time applications [1]. Several time frequency transforms are proposed earlier in which S-Transform is most popular technique used in signal analysis [2] [3] [4]. The S-Transform (ST), introduced by Stockwell et al.[5] is advanced method to short time Fourier transform(STFT) and continues wavelet transform(CWT) for progressive time frequency resolution [6] [7]. The involuntary resolution of STFT and insufficient of phase data in CWT results in development of ST [8] [9]. ST provides cumulative resolution property of CWT with globally referenced phase output [9]. During this progressive resolution energy concentration is major important factor for signal analysis [10]. Today in many of real time applications power spectral densities of signal are major requirement for signal analysis [11]. In such cases if the signal is contaminated by abrupt signal, ST suffers to provide time frequency analysis at faster rate due to lesser higher frequency localization [12] [13]. The following proposed method resolves spectral density components at a higher rate with accuracy resolution. This paper is organized as follows in section 2 gives complete details about analytical approach for how window includes nonlinearity of non stationary signal. Section 3 implements the physical method for proposed algorithm. Section 4 includes simulation results and discussions. Finally Section 5 contains conclusion and limitations.

2. Analytical approach identity

Stock well transform of a signal x(t) is given by
\[ S(t, f) = \int_{\infty}^{\infty} x(t)w(t - \tau, f)e^{j2\pi ft} dt; \]  

Where \[ w(t - \tau, f) = \frac{1}{\sqrt{2\pi f}} e^{j2\pi ft}; \]  

Standard deviation \[ \sigma(f) = \frac{1}{|f|}; \]

In this section an improved localization operators (t, f) are derived from the standard S-Transform with usual notations stated in [8, 9 and 14]. Let window function w ∈ R such that
\[ ||w||_b^H = 1. \]

By defining \[ 1 \leq S < \infty, \] the localization operator \[ S_{0,W} \] yields

\[ (S_{0,W})(b, \xi) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \sigma(b, \xi) dB d\xi; \]

\[ (S_{0,W})(b, \xi) = \frac{1}{c_n} \int_{-\infty}^{\infty} e^{j2\pi ft} \xi \int_{-\infty}^{\infty} \sigma(b, \xi); \]

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\[ (S_{0,W})(b, \xi) = \int_{-\infty}^{\infty} (S_{0,W})(b, \xi) e^{j2\pi ft} \xi \int_{-\infty}^{\infty} d\xi; \]

By using product theorem for Hilbert transform [16], localized operators in (8) can be turned as multi linear operators as follows

\[ (S_{0,W})(b, \xi) = \frac{1}{c_n} \int_{-\infty}^{\infty} (S_{0,W})(b, \xi) e^{j2\pi ft} \xi \int_{-\infty}^{\infty} d\xi; \]

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Where: σ = Standard deviation.
\( c_w = \) Normalized window coefficient.
ξ = Scaling parameter on frequency axis.
\( b = \) Scaling parameter on time axis.
α = Convolution property.

By Wigner transform [17], the window function can be localized in terms of signal complex conjugate model as follows:

\[
w(t, f) = \frac{1}{\sqrt{\pi b}} \int_{-\infty}^{\infty} x(t, b, \xi) x^*(f, b, \xi) db \, d\xi;
\]

(10)

The window width of the equation (10) can be considered as limitation since it will take into consideration the nature of analyzed signal. By including this window variation, finally the resultant multi local optimizations obtained as:

\[
\left(S_{\omega W}, t, f\right) = \frac{1}{c_{\omega W}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \omega(b, \xi) x(t, b, \xi) x^*(f, b, \xi) e^{-\frac{|f|^2}{(c_{\omega W})^2}} e^{-\frac{|f|^2}{\sigma^2}} db \, d\xi;
\]

(11)

By simplifying above equation finally

\[
\left(S_{\omega W}, t, f\right) = \frac{1}{c_{\omega W}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \omega(b, \xi) x_w(t, b, \xi) x_w^*(f, b, \xi) e^{-\frac{|f|^2}{(c_{\omega W})^2}} e^{-\frac{|f|^2}{\sigma^2}} db \, d\xi;
\]

(12)

The above mathematical formulation shows improved resolution consistency when compared with Standard S-Transform. It can be observed that window of the S-transform (12) accounts into the consideration of non stationary signal nature.

3. Physical method for proposed algorithm

In novel method of optimized frequency window proposed in [12, 13], a new differential frequency window is proposed in this section. The major aim of this window is to track all abrupt amplitude-frequency variations which exist in non stationary signal. One major problem during transform is whenever non stationary signal consists of abrupt amplitude variation equal to peak of gaussian window at initial intervals of gaussian function then some amplitude clipping during transform projection results in poor resolution. The same problem can also be observed at end intervals of gaussian window. To avoid this problem a parameter ‘β’ is included in standard S-Transform which makes variation in gaussian window shape. The proposed window major task is to maintain the neighboring frequencies of signal energy amplitudes should be projected to peak of gaussian and the energy contribution of each component would not exceed its window duration.

Steps for variation of ‘β’:

a) Take initially \( \beta_t = \frac{k}{(c+\alpha(\Delta t))}; k > 0; \)

(13)
b) Assume window as normalized interval [0 1]
c) Perform Newton Raphson iteration \( \beta_{t+1} = \beta_t - \frac{w(\Delta t)}{w'(\Delta t)}; \)

(14)
d) Above iteration is repeated until \( \beta_{t+1} \equiv \beta_t; \)

(15)

The window variations performed by Newton Raphson method [18] are taken from the section 2 (12) analytical identity which includes non linear variation of x (t). The term \( \Delta t \) indicates the bandwidth of the gaussian function and \( (\Delta t)^2 \) is fractional frequencies indulges in non linear periodic path of x (t). The complete physical significance of \( (\Delta t)^2 \) can be observed in [19] as it involves complex nature during transformation. In this way entire aperiodic path of x (t) is traced with peak of gaussian window until \( \beta_{t+1} \equiv \beta_t. \)

Finally improved S-Transform is given as

\[
S[t, f, \beta_t] = \int_{-\infty}^{\infty} x(t) \frac{|f|}{2\pi \beta_t} e^{-\frac{|f|^2}{\pi \beta_t}} e^{-j2\pi ft} dt;
\]

(16)

\[
S[t, f, \beta_t] = \int_{-\infty}^{\infty} x(t) \frac{|f|}{2\pi \beta_t} e^{-\frac{|f|^2}{\pi \beta_t}} e^{-j2\pi ft} dt;
\]

(17)

Thus \( w(t - t, f, \beta_t) = \frac{|f|}{2\pi \beta_t} e^{-\frac{|f|^2}{\pi \beta_t} }; \)

(19)

\( (\Delta f)^2 \) = Fractional frequency value at different ‘t’ intervals.

c = Y-axis intercept.
a = X-axis intercept.
k = Normalized amplitude value.

By substituting \( \beta_n \) (13) in (17) the resultant improved S-Transform is given as

\[
S[t, f, \beta_t] = \int_{-\infty}^{\infty} x(t) \frac{|f|}{2\pi \beta_t} e^{-\frac{|f|^2}{\pi \beta_t}} e^{-j2\pi ft} dt;
\]

(19)

Or

\[
S'[t, f, \beta_t] = \int_{-\infty}^{\infty} x(t) \frac{|f|}{2\pi \beta_t} (c + a(\Delta f)^2) e^{-\frac{|f|^2}{2\pi \beta_t} e^{-j2\pi ft} dt};
\]

(20)

The new window satisfies the normalization condition for the original S-transform window which ensures the invertibility of the modified S-transform given as

\[
f_{-\infty}^{\infty} w(t - t, f, \beta_t) \, dt = 1;
\]

(21)

Using the equivalent frequency domain definition of the Stockwell transform [8, 9], the improved discrete S-Transform is given as

\[
S'[f, n] = \sum_{m=0}^{N-1} X \left[ \frac{m+n}{N} \right] e^{-2\pi i \frac{(m+n)^2}{N}} e^{-j\frac{2\pi kn}{N}} \frac{1}{2\pi \beta_t} e^{-j2\pi ft} dt;
\]

(22)

Where: Input = x (m); m = 0, 1, 2,..., N-1; H(.) is the Discrete Fourier Transform (DFT) of h(.) defined for p=0, 1, 2,..., N-1; Empirically the values of c, a and k may not be adequate for some types of signals. It will be more appropriate to generate automatically adaptive parameters which respect the nature of analyzed signal. A Recursive Genetic Algorithm (RGA) [20] is used to select automatically the parameters c, a and k. Initially a test vector of values c, a and k are generated using Genetic algorithm. Where Genetic Algorithm (GA) is based on the mechanisms of natural selection and genetics has been developed since 1975 [20, 21]. RGA has been proven to be very efficient and stable in searching for global optimum solutions. Usually, a simple GA is mainly composed of three operations: selection, genetic operation, and replacement. A recursive fitness proportionate function is adapted for optimization [20, 21]. This fitness proportionate function will acts as feedback loop. The above process is repeated until achievement of optimized values c, a and k with respect to standard GA algorithm values.

The complete flow graph model of RGA is shown in Fig. 1. Optimized model.
Finally as per in view of real time applications concerned, the proposed window transform is implemented on FPGA by using Xilinx 14.1 SPARTAN XC3S4000 [23]. The complete design flow of the FPGA implementations is as shown in Fig.2. Where input buffer consist of Non stationary and window transform values. These values are transferred to the Xilinx Processor. The 12 bit output from processor is fed to DAC and output is viewed in CRO. For these transformation conversions CARDIAC algorithm is used for VHDL implementation [24].

4. Simulation results and discussions

In this section, performance of proposed algorithm for the S-Transform is examined. Initially the proposed algorithm is tested for sample ECG data and compared with other TFRs: a) Short Time Fourier Transform (STFT), b) Wigner-Ville distribution (WVD) c) Standard S-Transform, d) Modified S-Transform [12], e) Proposed S-Transform (22).

Test1:- Input: ECG data

From the results it can be concluded that TFR resolution of Modified S - Transform [12] and Proposed S-Transform are similar, better when compared with the STFT, WVD and Standard S-Transform. But the advantage of proposed S-Transform is when the signal is attacked suddenly with abrupt changes (abnormal changes) then the change of abnormality is traced faster when compared with other TFRs.

Test2:- An abrupt change of ECG data during transformation is considered and performed TFRs. A particular concentration of Modified S-Transform [12] and Proposed S-Transform (22) has been evaluated with different elapsed time delay intervals.

i) Case at τ=0.521ms

From Fig. 4. It can be observed that small sign of indication for abrupt variation in proposed S-Transform (22) but it was not found in Modified S-Transform [12].

ii) Case at τ=1.054ms
From Fig. 5. It can be observed that proposed S-Transform (22) gives better localization when compared with Modified S-Transform [12].

iii) Case at τ=1.640ms

Fig. 6. Result shows that proposed algorithm (22) gives better resolution for abrupt changes in estimated instantaneous amplitude-instantaneous frequency (IF) values [10]. A sample variation of Gaussian window with respect to ‘βn’ during transform is shown in Fig. 7.

Furthermore the time delay taken for complete transformation of proposed algorithm is less when compared with other TFRs. Table 1. Shows Concentric Metric Measures (CMM) of proposed algorithm with other TFRs.

<table>
<thead>
<tr>
<th>CMM</th>
<th>STFT</th>
<th>WVD</th>
<th>S-Transform</th>
<th>Modified S-Transform [18]</th>
<th>Proposed S-Transform</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abrupt peak-Pixel Resolution (Mean)</td>
<td>0.5254</td>
<td>0.5145</td>
<td>0.3645</td>
<td>0.2232</td>
<td>0.2012</td>
</tr>
<tr>
<td>Abrupt peak-Pixel Resolution (Standard Deviation)</td>
<td>0.4213</td>
<td>0.3945</td>
<td>0.2554</td>
<td>0.1942</td>
<td>0.1524</td>
</tr>
<tr>
<td>Delay (ms)</td>
<td>2.284</td>
<td>2.021</td>
<td>1.912</td>
<td>1.642</td>
<td>1.562</td>
</tr>
</tbody>
</table>

Finally proposed algorithm is examined in presence of noise. Accuracy of the instantaneous frequency estimation based on peak values is observed [10]. A sample of ECG data [29] is taken and contaminated with additive white gaussian noise (AWGN) and performed signal to noise ratio (SNR) versus Mean Square Error (MSE).

Where

\[
\text{SNR} = 10 \log_{10} \left( \frac{A^2}{\sigma_n^2} \right)
\]

(23)

\[
\sigma_n^2 = \text{Variance of the noise.}
\]

\[
A = \text{Signal amplitude (Normalized value ‘1’)}.
\]
5. Conclusion

In this paper, a differential frequency window S-Transform is proposed. The proposed algorithm is evaluated with other TFRs. Under normal environment conditions proposed algorithm TFR is equivalent to modified S-Transform [12]. But the proposed algorithm gives improved results in abrupt environment when compared with other TFRs. An attempt of non stationary signal behavior is considered by proposed window with localization parameters. Moreover it was observed that proposed method produces less MSE when compared with other TFRs. But the major limitation of proposed method is when $\beta$ goes for higher order Newton Raphson method then delay factor increases enormously.

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References


