Reduction of SSR oscillations in power system network with STATCOM and UPFC

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Abstract

SSR is a complex issue in electric power transmission network because of which the mechanical arrangement of a multi mass model encounters shaft harms. To keep away from this issue the mechanical oscillations which for the most part happen amid a balanced short circuit fault on the transmission network ought to be moderated by a few means. This paper delineates about the IEEE second benchmark framework which is demonstrated and simulated in MATLAB Simulink. The outcomes are compared when Static Synchronous Compensator (STATCOM) is incorporated and furthermore with those when Unified Power Flow Controller (UPFC) included for their viability in moderating the Subsynchronous Resonance motions.

Keywords: Flexible AC Transmission Systems, SSR, STATCOM, UPFC.

1. Preface

In present electric power system networks, sub synchronous resonance (SSR) is a serious problem which makes the system unstable in the event of faults due to the presence of series capacitors. Due to this phenomenon, the shaft mechanism undergoes undamped oscillations which may cause total shaft failure. As per theory, it happens, when the electric network transfers energy with a turbine generator at one or more of the regular frequencies of the connected network beneath the system frequency[1]. To analyze the problem of SSR, some standard test cases were prepared by the IEEE SSR task force [2-3]. In this model, six masses coupled to the same shaft namely ‘High Pressure’, ‘Intermediate Pressure’, ‘Low Pressure A’, ‘Low Pressure B’, ‘Generator’ and ‘Exciter’. These are interconnected with transmission network viz. a 600 MVA, 22500 kV transformer. This model is developed in MATLAB and is simulated for analysis [3].

For minimizing the SSR oscillations, FACTS like STATCOM and UPFC can be included in parallel with the series capacitor. V-I characteristic for a STATCOM is like that of a synchronous condenser, yet it has no inertia and is profitable in different perspectives over the synchronous condenser, for example, better dynamics, a low speculation cost and diminished working and maintenance costs. Control analyses for systems [10-19].

A STATCOM is comprised of Thyristors with great turn-off capability such as GTO or an Insulated Gate Controlled Thyristor or with large number of IGBTs. STATCOM has a merit that the variation of reactive power is independent of the real voltage at the supply. This aspect is viewed in the figure 1 where the maximum currents flowing are independent of the voltage in contrast with the SVC.

This implies, that amid most severe fault conditions, the STATCOM works with full capability.

2. Principle of Operation of STATCOM

Fig.2 shows a three phase six pulse STATCOM. Here, in the event that voltage of STATCOM ‘Vs’ is more in contrast with bus voltage, ‘Es’, at that point capacitive or leading VArS are generated and if ‘Vs’ is lesser than ‘Es’ then inductive or lagging VArS are generated.
The STATCOM shown in Fig. 2 operates according to the principle that, for a three phase power system network operating at system frequency in steady state, the average power flowing into a pure reactive component should become nullified at any instant.

In present case, each phase receives V-Ars which can be generated at every instant by circulating the real power between the phases which is instantaneous. To achieve this, proper firing of the Gate Turn Off/diode switches should be done in such a way so as to maintain the difference in phase angles of bus voltage ‘Es’ and ‘Vs’ at every instant.

Based on circulating instantaneous power criteria, a device can be built without any energy storage element. Figure 3 shows a MATLAB Simulink model similar to the IEEE Second benchmark system is first developed including the STATCOM across the series capacitor used for compensation [4]. The results after simulation are shown in Fig. 4. From the figure, it seems that the Subsynchronous Resonance oscillations between Low Pressure – High Pressure turbines are reduced gradually and are limited less than 1 p.u. Observing the graph it can be seen that with addition of STATCOM the Subsynchronous Resonance currents are lessened and so the torque oscillations are restricted to lie within limits.

Fig. 2: STATCOM with Three Phase six pulse

Fig. 3: Simulation circuit for the IEEE SBM system with STATCOM
Fig. 4: Gen, LP, HP turbine outputs with respect to time with STATCOM
A basic UPFC is made up of shunt transformer and series transformer. These transformers are linked through two VSCs having a typical DC link capacitor. Exchange of real power between shunt transformer and series transformers is allowed in the DC circuit to control phase angle shift of the series voltage. The basic UPFC arrangement is as shown in figure 6. It gives the full controllability for voltage and power flow. A thyristor bridge is used to protect the series converter.

3. Operating Principle of UPFC

An UPFC has basic components such as two voltage source inverters that share a common dc storage capacitor. These are connected to the power system network via coupling transformers. One of the voltage source inverters is linked to in shunt to the power transmission network through a shunt transformer, while the other VSI is linked in series through a series transformer. Fig. 7 shows a basic Unified Power Flow Controller functional scheme.
4. Results

The results after MATLAB simulation are given in Table I. It gives a comparison about the reduction in maximum amplitudes of torque pulsations and the changes in angular speeds of various masses without inclusion of FACTS controllers where the SSR oscillations are uncontrolled. Then the same results are compared including STATCOM and UPFC. Here, from the table, it is clear that the effectiveness in damping SSR oscillations is more as the magnitudes of oscillations are lessened to a smaller value with inclusion of UPFC in contrast to STATCOM.
Fig. 9: Gen, LP, HP turbine outputs with respect to time with Unified Power Flow Controller
Fig. 10: $V_L$(p.u.), $I_L$(A), $V_C$ and fault current wave forms with respect time with Unified Power Flow Controller
Table I Torque Pulsation Magnitudes And Angular Speed Deviations For The Three Cases
5. Conclusions

In this paper, an effort is made to illustrate the comparison in effectiveness of UPFC and STATCOM in mitigating the SSR oscillations that are present in the power system network during transients. Three cases are examined to study the turbine torques variations and angular speeds changes:
1. With no FACTS controller.
2. When STATCOM is included and
3. When UPFC is included.

The results given in section IV clearly indicates how the UPFC can reduce the torque pulsations between various shafts of the multi mass model, as well as changes in angular speeds in generator, low pressure and high pressure turbines more effectively than STATCOM. Improvement in the power system network is noticed with inclusion of UPFC rather than STATCOM. But there is a need for compromise between the economy and network performance as UPFC is costlier than compared to STATCOM.

6. Appendix

Parameters of AC system:
Voltage of transmission: 500 kilovolts
Supply frequency: 50 Hz

(a) Transmission lines Parameters (3 ph):
R per km: 0.02 Ω,
L per km: 0.9 Henry
C per km: 13 μF,
Transmission Line length: 200 km
Xc: 30 percent of XL.

(b) Alternator details:
Rated Power: 600MVA
Line to Line voltage: 22 kV
Reactances: Xd = 1.65, Xd’ = 0.25, Xd” = 0.2, Xq = 1.59, Xq’ = 0.46, Xq” = 0.2
Time Constants:
Tdo’ = 4.5 sec, Tdo’’ = 0.04 sec, Tqo’ = 0.67 sec, Tqo’’ = 0.09 sec
Resistance of stator = 0.0045 pu

(c) Power Transformer Details:
Nominal Power: 600 Mega volt amperes (3 ph)
Voltage rating: 22kV/500kV (Line-Line)

References


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