



Numerical Solution of Time Fractional Parabolic Differential Equations

T.R.Ramesh Rao

¹B.S.Abdur Rahman Crescent Institute of Science and Technology, Chennai, India 600048.

*Corresponding author E-mail: rameshrao@crescent.education

Abstract

In this paper, we study the coupling of an approximate analytical technique called reduced differential transform (RDT) with fractional complex transform. The present method reduces the time fractional differential equations in to integer order differential equations. The fractional derivatives are defined in Jumaries modified Riemann-Liouville sense. Result shows that the present technique is effective and powerful for handling the fractional order differential equations.

Keywords: Reduced differential transform, fractional derivatives, Riemann-Liouville's fractional derivatives.

1. Introduction

In recent years, the fractional calculus [1, 2, 3, 4,12] is an interesting topic in current literature. It has attracted many researchers because of its wide application in diverse fields of engineering and physical sciences. The fractional calculus involves different definitions of the fractional differential operators namely Riemann-Liouville's derivatives, Caputo derivatives, Riez and Grunwald-Letnikov derivatives. Most of the authors follow the caputo or Riemann – Liouville's form of fractional derivatives to solve the fractional differential equations because their solutions are practically useful. For example Guy Jumarie [15] proposed a new method obtained by using modified Riemann-Liouville derivatives to solve the fractional nonlinear partial differential equations. Later Zheng-Biao Li et al [9, 13, 16] proposed fractional complex transform method based on modified Riemann-Liouville derivatives, a novel and universal approach for finding exact solutions of fractional differential equations. Later, many researchers [10, 11] have explored this topic and applied this technique to solve mathematical models based on fractional calculus.

2. Jumaries Riemann-Liouville Fractional Derivatives

$$D_t^\beta f(t) = \begin{cases} \frac{1}{\Gamma(-\beta)} \int_0^t (t-\tau)^{-\beta-1} [f(\tau) - f(0)] d\tau & \beta < 0 \\ \frac{1}{\Gamma(-\beta)} \frac{d}{dt} \int_0^t (t-\tau)^{-\beta-1} [f(\tau) - f(0)] d\tau, & 0 < \beta < 1 \\ [f^{(\beta-m)}(t)]^{(m)}, & m \leq \beta \leq m+1, m \geq 1 \end{cases} \quad (1)$$

where $f: R \rightarrow R$ is a continuous function.

Here, we mention some important properties of the modified Riemann-Liouville's derivatives [14]:

$$(i) D_t^\beta (c) = 0, \alpha > 0, c \text{ is a constant}$$

$$(ii) D_t^\beta [cf(t)] = cD_t^\beta f(t), \alpha > 0$$

$$(iii) D_t^\beta t^\alpha = \frac{\Gamma(1+\alpha)}{\Gamma(1+\alpha-\beta)} t^{\alpha-\beta}, \alpha > \beta > 0$$

$$(iv) D_t^\beta [f(t)g(t)] = [D_t^\beta f(t)]g(t) + f(t)[D_t^\beta g(t)]$$

$$(v) D_t^\beta [f(h(t))] = f'_h(h(t))D_t^\beta h(t)$$

3. Fractional complex transform

$$T = \frac{kt^{\alpha_1}}{\Gamma(1+\alpha_1)} \quad (2)$$

$$X = \frac{lx^{\alpha_2}}{\Gamma(1+\alpha_2)} \quad (3)$$

$$Y = \frac{my^{\alpha_3}}{\Gamma(1+\alpha_3)} \quad (4)$$

$$Z = \frac{nz^{\alpha_4}}{\Gamma(1+\alpha_4)} \quad (5)$$

where k, l, m, n are unknown constants and $0 < \alpha_1 \leq 1,$

$0 < \alpha_2 \leq 1, 0 < \alpha_3 \leq 1, 0 < \alpha_4 \leq 1.$

4. Outline of the method

The basic definition and properties of reduced differential transform (RDT) are given in [8].

The reduced differential transform of $v(x, t)$ at $t = 0$ is defined as

$$V_k(x) = \frac{1}{k!} \left[\frac{\partial^k v(x, t)}{\partial x^k} \right]_{t=0} \quad (7)$$

The differential inverse transform of $V_k(x)$ is defined as

$$v(x, t) = \sum_{k=0}^{\infty} V_k(x) t^k \quad (8)$$

and from (7) and (8), we have

$$v(x, t) = \sum_{k=0}^{\infty} \frac{1}{k!} \left[\frac{\partial^k v(x, t)}{\partial x^k} \right]_{t=0} t^k$$

Theorem 1. If $w(x, t) = u(x, t) \pm v(x, t)$ then

$$W_k(x) = U_k(x) \pm V_k(x)$$

Theorem 2. If $w(x, t) = mv(x, t)$ then $W_k(x) = mV_k(x)$

Theorem 3. If $w(x, t) = m \frac{\partial^p v(x, t)}{\partial t^p}$ then

$$W_k(x) = m \frac{(k+p)!}{k!} V_{k+p}(x)$$

Theorem 4. If $w(x, t) = x^p t^q$ then

$$W_k(x) = x^p \delta(k-q) = \begin{cases} x^p & \text{if } k = q \\ 0 & \text{if } k \neq q \end{cases}$$

Theorem 5. If $w(x, t) = m \frac{\partial^p u(x, t)}{\partial x^p}$ then $W_k(x) = m \frac{\partial^p U_k(x)}{\partial x^p}$

Theorem 6. If $w(x, t) = u(x, t)v(x, t)$ then

$$W_k(x) = \sum_{p=0}^k U_p(x)V_{k-p}(x)$$

Theorem 7. If $w(x, t) = x^p t^q u(x, t)$ then

$$W_k(x) = x^p U_{k-q}(x)$$

Theorem 8. If $w(x, t) = t^q u(x, t)$ then

$$W_k(x) = V_{k-q}(x)$$

Theorem 9. If $v(x, t) = e^{au(x, t)}$ then

$$V_k(x) = \begin{cases} e^{aU_0(x)} & \text{if } k=0 \\ a \sum_{k_1=0}^k \left(1 - \frac{k_1}{k}\right) V_{k_1}(x) U_{k-k_1}(x) & \text{if } k \geq 1 \end{cases}$$

The main objective of this work is to illustrate the ability and reliability of fractional complex transform based on Jumarie's modified Riemann-Liouville derivatives to achieve the explicit solution of time fractional parabolic equations via the method of RDT

5. Numerical Applications

Example 5.1 Consider the time fractional parabolic equation:

$$D_t^\beta v = v_{xx} + e^{-v} + e^{-2v}, \quad (x, t) \in [0,1] \times [0,1] \tag{10}$$

with initial condition

$$v(x, 0) = \log(x + 2) \tag{11}$$

Using the complex transformation [15], we obtain the following integer order PDE:

$$\frac{\partial v}{\partial T} = v_{xx} + e^{-v} + e^{-2v} \tag{12}$$

Operating differential transform on (12) and using the theorem (9), we obtained the following recurrence formula

$$(k + 1)V_{k+1}(x) = \frac{\partial^2}{\partial x^2} V_k(x) + W_k(x) + G_k(x) \tag{13}$$

From the initial condition (11), we have

$$V_0(x) = \log(x + 2) \tag{14}$$

Where

$$W_k(x) = RDT(e^{-v}) = \begin{cases} e^{-v_0} & \text{if } k = 0 \\ -\sum_{k_1=0}^{k-1} \left(1 - \frac{k_1}{k}\right) W_{k_1}(x) V_{k-k_1}(x) & \text{if } k > 0 \end{cases}$$

$$G_k(x) = RDT(e^{-2v}) = \begin{cases} e^{-2v_0} & \text{if } k = 0 \\ -2 \sum_{k_1=0}^{k-1} \left(1 - \frac{k_1}{k}\right) G_{k_1}(x) V_{k-k_1}(x) & \text{if } k > 0 \end{cases} \tag{16}$$

Substituting the eqn. (14) in to the eqn. (13) and then using the transformed equations (15) and (16), for $k = 0, 1, 2, 3, 4$, the first few components of $U_k(x)$ are obtained as follows:

$$V_1(x) = \frac{\partial^2}{\partial x^2} V_0(x) + W_0(x) + G_0(x) \tag{9}$$

$$V_1(x) = \frac{1}{x+2} \tag{17}$$

$$2V_2(x) = \frac{\partial^2}{\partial x^2} V_1(x) - W_0 U_1 - 2G_0 V_1$$

$$V_2(x) = -\frac{1}{4(x+2)^2} \tag{18}$$

$$3V_3(x) = \frac{\partial^2}{\partial x^2} V_2 - W_0 V_2 - \frac{1}{2} W_1 V_1 - 2G_0 V_2 - G_1 V_1$$

$$V_3(x) = \frac{1}{9(x+2)^3} \tag{19}$$

$$4V_4(x) = \frac{\partial^2}{\partial x^2} V_3 - W_0 V_3 - \frac{2}{3} W_1 V_2 - \frac{1}{3} W_2 V_1 - 2G_0 V_3 - \frac{4}{3} G_1 V_2 - \frac{2}{3} G_2 V_1$$

$$V_4(x) = -\frac{1}{16(x+2)^4} \tag{20}$$

$$5V_5(x) = \frac{\partial^2}{\partial x^2} V_4 - W_0 V_4 - \frac{3}{4} W_1 V_3 - \frac{1}{2} W_2 V_2 - \frac{1}{4} W_3 V_1$$

$$-2G_0 V_4 - \frac{3}{2} G_1 V_3 - G_2 V_2 - \frac{1}{2} G_3 V_1 - G_2 V_2 - \frac{1}{2} G_3 V_1$$

$$V_5(x) = \frac{1}{25(x+2)^5} \tag{21}$$

Now, substituting the Eqns. (17) - (21) in to the Eqn. (9), we have

$$v(x, t) = \log \left(x + \frac{t^\beta}{\Gamma(1+\beta)} + 2 \right) \tag{22}$$

which is exactly the same as the results obtained by Galerkin collocation method [5,6] and ADM [7] when $\beta = 1$.

Example 5.2 The time fractional parabolic equation

$$x D_t^\beta v = v_{xx} + v^2, \quad (x, t) \in [0,1] \times [0,1] \tag{23}$$

with initial condition

$$v(x, 0) = x \tag{24}$$

Using the complex transformation [15], we obtain the following integer order PDE:

$$x \frac{\partial v}{\partial T} = v_{xx} + v^2 \tag{25}$$

Operating differential transform on (25) and using the theorem (6), we obtained the following recurrence formula:

$$(k + 1)xV_{k+1}(x) = \frac{\partial^2}{\partial x^2} V_k(x) + \sum_{k_1=0}^k V_{k_1}(x) V_{k-k_1}(x) \tag{26}$$

From the initial condition of Eqn. (25), we have

$$V_0(x) = x \tag{27}$$

According to RDT, using the recursive formula (26) and the initial condition (27), we obtain

$$V_k(x) = x \text{ for } k = 1, 2, 3, 4 \dots \tag{28}$$

(14) This implies

$$v(x, t) = x + xT + xT^2 + xT^3 + \dots$$

Since $0 < T < 1$

$$= \frac{x}{1-T} = \frac{x}{1 - \left(\frac{t^\beta}{\Gamma(1+\beta)}\right)} \tag{29}$$

which is exactly the same as the results obtained by ADM [17] when $\beta = 1$.

6. Conclusion

In this work, we successfully presented the coupling technique to achieve the analytical solution of fractional parabolic differential equations. The fractional complex transform requires no special

knowledge of fractional calculus and it is extremely accessible to solve other similar type of nonlinear fractional differential equations.

References

- [1] Kilbas AA, Srivastava HM & Trujillo JJ, Theory and Applications of Fractional Differential Equations, Elsevier(North h-Holland), Sci. Publishers, Amsterdam (2006).
- [2] Podlubny I, Fractional Differential Equations, Academic Press, New York (1999).
- [3] Sabatier J, Agrawal OP & Tenreiro Machado JA, Advances in Fractional Calculus: Theoretical Developments and Applications in Physics and Engineering, Springer, Dordrecht (2007)
- [4] Miller KS & Ross B, An Introduction to the Fractional Calculus and Fractional Differential Equations, Wiley, New York (1993)
- [5] Fletcher, CAJ, Computational Galerkin Methods, Springer-verlag, New York, First Edition, (1984)
- [6] Hopkins TR & Wait R, "A comparison of galerkin collocation and the method of lines for PDE's", Int. J. Numer. Meth. Engin., Vol. 12 (1978), pp: 1081-1107.
- [7] Javidhi M & Golbabbai A, "Adomian decomposition method for approximating the solution of the parabolic equations", Applies Mathematical Sciences, Vol. 1, No. 5 (2007), pp: 219-225.
- [8] Keskin Y & GalipOturanc, "Reduced differential transform method for partial differential equations", Int. Journal of nonlinear sciences and numerical simulation, Vol. 10, No. 6 (2009), pp: 741-749.
- [9] Zheng-Biao Li & Ji-Huan He, "Application of the Fractional Complex Transform to Fractional Differential Equations", Non-linear Sci.Lett.A, Vol. 2 (2011), pp:121-126.
- [10] Rabha W Ibrahim, "Fractional complex transforms for fractional differential equations", Advances in Difference Equations, Vol. 2012 (2012), pp: 192.
- [11] Elsayed M.E.Zayed, Yasser A.Amer & Reham M.A.Shohib, "The fractional complex transformation for nonlinear fractional partial differential equations in the mathematical physics", Journal of the Association of Arab Universities for Basic and Applied Sciences, (2014) (article in press).
- [12] Saha Ray S & Sahoo, S, "A Novel Analytical Method with fractional complex transform for new exact solutions of time-fractional fifth-order Swada-Kotera Equation", Reports on Mathematical Physics, Vol. 75 (2015), pp: 65-72.
- [13] Zheng-Biao Li, "An Extended Fractional Complex Transform", International Journal of Nonlinear Sciences & Simulation, Vol. 11 (2010), pp: 335-337.
- [14] Ji-Huan He, Elagan SK & Li ZB, "Geometrical explanation of the fractional complex transform and derivative chain rule for fractional calculus", Physics Letters A, Vol. 376 (2012), pp: 257-259.
- [15] Guy Jumarie, "Fractional partial differential equations and modified Riemann-Liouville derivatives new methods for solution", J.Appl.Math.& Comp, Vol 24 (2007), pp: 31-48.
- [16] Zeng Biao Li & Ji-Juan He, "Fractional complex transform for fractional differential equation", Mathematical and Computational Applications, Vol. 15 (2010), pp: 970-973.
- [17] Soufyane A & Boulmalf M, "Solution of linear and nonlinear parabolic equations by decomposition method", Journal of Applied Mathematics and Computation, Vol. 162 (2005), pp: 687-693.