Analysis on nonlinear stability of the triangular libration points for radiating and oblate primaries in ER3BP

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Abstract

In this paper we study the non linear stability of the triangular librations points in ER3BP considering both the primaries as radiating and oblate. The study is carried out near the resonance frequency satisfying the conditions $\omega_1 = \omega_2, \omega_0 = 2\omega_2, \omega_3 = 3\omega_2$ in resonance as well as non resonance case. The study is conducted for various values of radiation pressure and oblateness parameters. It is observed that the case $\omega_0 = \omega_3$ corresponds to the boundary region of the stability for the system, further it is examined that the system experiences resonance at $\omega_0 = 2\omega_2, \omega_0 = 3\omega_2$ for different values of radiation pressures and oblateness parameter. In non-resonance case, it is observed that the equilibrium points are stable. In resonance case, for $\mu_1, \mu_2 = 0.0385209$, and $\omega_0 = \omega_2$ the triangular equilibrium points are unstable. In case, when $\omega_0 = 3\omega_2$ for some values of radiation pressure and oblateness parameter, it is stable and for some of the values of the parameters it is unstable. The model is best suited to the binary systems (Achird, Luyten, α Cen AB, Kruger- 60, Xi- Bootis).

Keywords: Er3bp; Hamiltonian Functions; Triangular Libration Points; Resonance;Kam Theory.

1. Introduction

One of the most famous and historically investigated chaotic dynamical systems is the elliptical restricted problem of three bodies (ER3BP) due to its application in dynamical astronomy, celestial mechanics and space mechanics. It constitute a major source of interesting theories in lunar and planetary sciences. The ER3BP describes the three dimensional motion of small particle called the infinitesimal mass under the gravitational force of two finite bodies called primaries around their common centre of mass. A typical example of the ER3BP is the motion of an asteroid under the gravitational attraction of the Sun and the Jupiter. The orbital motion of the Earth- Moon System around the Sun and the motion of thousands of astronomical and astrophysical bodies such as satellites, binary pulsars and the Moon have attracted attention and many studies has been conducted out in the model of ER3BP. The equilibrium points that appeared in ERTBP are very important for astronomical applications as space station can be easily located at these points due to minimum consumption of fuel, which is required for station keeping.

Many researchers considered the primaries and the third body to be either a point mass or spherical but later on it has been found that in general, celestial or stellar bodies are sufficiently oblate in shape which plays a significant role in restricted three body problem. Some of the planets such as Earth, Saturn, Jupiter and stars namely Achernar, Regulus, Vega, Alfa Arae and Altair are oblate showing the deviated behavior from spherical shape having a significant impact in restricted three body problem. Since, the rotation of stars is very fast, equatorial bulges is formed and are responsible for oblate shape of neutrons stars, pulsars, white and brown dwarf stars. Many stars belong to binary system; hence the motion of a particle in the field of double star has created special interest in space dynamics. High mass X-ray binaries after common envelope evolution and spiral in, produces double neutron star binaries. Fast spinning “recycled pulsars in binary systems provides good source to study the orbital kinematics. Einstein theory of relativity and theoretical gravitational waves can be applied to the double pulsars where warped space time due to shift of intense masses is extremely rare. [1] It is found that pulsars and their orbiting companions are compact enough to be treated as two point masses. Along with [2,3] many others researchers found that some planets exist outside our solar system and confirmed that PSR B1257+12 and PSR B1620-26 possess extra solar planets orbiting them. In the stellar system, a planet moving in the field of binary star forms three body problem; providing a premise to study fundamental physics and to test alternative gravities as given by [4,5]. A planet in the neighborhood of any of the following PSR B1534+12, PSR B1913+16, PSR B1620+26, PSR 1257+13, PSR J1022+1002, PSR J1518+4904, PSR B1534+12, PSR B2127+11C, PSR 2303+46 and others provide an excellent models for elliptical restricted three body problem.

The nonlinear stability of an elliptical or circular restricted three body problem of a Hamiltonian system is generally performed by using Kolmogorov-Arnold-Moser (KAM) theorem in non-resonance case and by Markeev theorem in resonance case. Taking one of the bodies as radiating, the nonlinear stability of the triangular equilibrium points for resonance and non-resonance conditions was studied by [6]. Considering both the bodies as radiating in circular restricted three body problem, [7, 8] examined the stability of the triangular equilibrium points for non-resonance as well as resonance case. [9] Discussed the nonlinear stability of the triangular equilibrium points in circular restricted three bodies, considering bigger primary as a source of radiation.
The nonlinear stability of the triangular Lagrangian points, considering
the bigger primary as oblatespheroid in circular case was
examined by [10].

The ER3BP are studied by [11-26]. The present paper investigates
the stability of the infinitesimal mass about the triangular equilibrium
points in both resonance and non-resonance case satisfying
\( \omega_0 = \omega_1, \omega_0 = 2\omega_2, \omega_0 = 3\omega_2 \) in ER3BP The study is carried out at
various values of radiation pressures and oblateness parameter.

This paper has been organized in various sections:
Section 1 gives introduction, section 2 describes the equations of
motion of the problem, section 3 deals with characteristics roots
and first order stability of the triangular equilibrium points. The
existence of resonance is discussed in section 4, while section 5
deals with normalization and higher order stability of the libration
points in non-resonance case. Stability in resonance case is dis-

cussed in section 6. Finally section 7 summarizes the discussion and
conclusion of the paper.

2. Equations of motion

The differential equations of the motion of the infinitesimal mass
in elliptical restricted three body problem under radiating prima-
ries in pulsating system as given by Narayan and Shrivastava [27]
is:

\[
x' = 2y' = \varphi \Omega_x ;
\]

\[
y' = 2x' = \varphi \Omega_y
\]

(1)

where the force function is defined as:

\[
\Omega = \frac{x^2 + y^2}{2} - \frac{1}{1 + \frac{1}{3} \left( \frac{A_1 + A_2}{2} \right)} \times \left[ \frac{(1 - \mu)Q_1}{\eta} \frac{\mu Q_2}{\eta^2} + \frac{(1 - \mu)Q_1 A_1}{2\eta^3} + \frac{\mu A_2 Q_2}{2\eta^2} \right]
\]

(2)

\[
\eta^2 = (x + \mu)^2 + y^2 ;
\]

\[
\eta^2 = (x - 1 + \mu)^2 + y^2 ;
\]

(3)

\[
\varphi = \frac{1}{(1 + \epsilon \cos f)}
\]

(4)

\( Q_i = 1 - \beta_i, \, i = 1, 2) \) The radiation pressure, \( \epsilon \) a true anomaly of the
primariesand \( A_1, A_2 \) the oblateness parameter.

The coordinates of the triangular equilibrium points L4 and L5 as
given by: Narayan and Shrivastava [27] is:

\[
x_0 = \frac{1}{2} - \mu + \frac{A_1}{2} + \frac{A_2}{2} - \frac{\beta_1}{3} - \frac{\beta_2}{3} \\
\frac{1}{2} A_1 \beta_1 + \frac{1}{2} A_2 \beta_2 ;
\]

\[
y_0 = \pm \sqrt{2} \left[ \frac{1}{3} A_1 \beta_1 - \frac{1}{3} A_2 \beta_2 \right]
\]

(5)

3. Characteristics roots and first order stability
of the triangular equilibrium points

The stability of the elliptical restricted three body problem is re-
stricted to planar case only. It is sufficient to study the stability of the
triangular equilibrium points about L4 due to similar of Ls and
L5. The Hamiltonian as described by Narayan and Shrivastava
[27] is given by:

\[
H = \sum_{K=0}^{\infty} K_0 + H_1 + H_2 + H_3
\]

+H_4 + .........

where

\[
H_0 = H(\xi, \eta, p_\xi, p_\eta) = \text{constant}; \, H_1 = 0 .
\]

and by substituting \( Q_i = 1 - \beta_i, \, i = 1, 2) \) we have:

\[
H = \frac{p^2}{2} + (p_\eta q_\eta - p_\xi q_\xi)
\]

\[
= \frac{(q_1^2 + q_2^2) \cos f}{2(1 + \epsilon \cos f)} \left[ \frac{1}{1 + \frac{1}{3} \frac{A_1 + A_2}{2}} \right] \times \left[ \frac{(1 - \mu)Q_1}{\eta} \frac{\mu Q_2}{\eta^2} + \frac{(1 - \mu)Q_1 A_1}{2\eta^3} + \frac{\mu A_2 Q_2}{2\eta^2} \right]
\]

(6)

Now expanding the Hamiltonian function given by equation (6) in
the powers of \( p_i \) and \( q_i \):

\[
H = \sum_{K=0}^{\infty} H_K = H_0 + H_1 + H_2 + H_3
\]

Further by using Taylor’s theorem and equating the coefficients of
2nd, 3rd, 4th order from the above equation (7) we have:

Further by using Taylor’s theorem and equating the coefficients of
2nd, 3rd, 4th order from the above equation (7) we have:
\[ H_2 = \frac{p_1^2 + p_2^2}{2} + (p_1 q_2 - p_2 q_1) + \]
\[ e \cos f \left( \frac{q_1^2 + q_2^2}{2(1 + e \cos f)} \right) - \frac{1}{2(1 + e \cos f)} (H_{20} q_1^2 - H_{11} q_1 q_2 - H_{02} q_2^2) \]

where

\[ H_{20} = \begin{bmatrix}
-1 & 9 & 8 & A_1 & 9 & 8 & A_2 & -7 & 3 & A_1 & + & 11 & 9 & A_2 & B_2 \\
-27 & 8 & A_1 & + & 27 & 8 & A_2 & + & 17 & 8 & A_1 & - & 7 & 9 & A_2 & B_2 \\
-\frac{1}{2} & 18 & B_2 & \end{bmatrix} \]

\[ H_{11} = \begin{bmatrix}
3 & 17 & 8 & A_1 & + & 7 & 8 & A_2 & + & 13 & 9 & A_1 & B_2 \\
15 & 8 & A_2 & B_2 & - & 41 & 8 & A_1 & - & 41 & 8 & A_2 & - & 1 & 6 & B_2 \\
+ & 1 & B_2 & & + & 3 & B_2 & \cdot & 7 & 12 & B_2 \\
-3 & 18 & B_2 & & - & 3 & 18 & B_2 & & + & 3 & 18 & B_2 \\
\end{bmatrix} \]

\[ H_{02} = \begin{bmatrix}
5 & 27 & 8 & A_1 & + & 21 & 8 & A_2 & + & 107 & 16 & A_1 & B_2 & + & 11 & 16 & A_2 & B_2 \\
-33 & 18 & A_1 & + & 33 & 18 & A_2 & + & 7 & 8 & A_1 & B_2 & + & 11 & 8 & A_2 & B_2 \\
\frac{1}{2} & 18 & B_2 & \end{bmatrix} \]

Also,

\[ H_3 = \frac{1}{6(1 + e \cos f) (1 + 3(A_1 + A_2)/2)} \]

\[ q_1^2 \times \begin{bmatrix}
-21 & 15 & A_1 & + & 9 & 1 & A_2 & - & 11 & 3 & B_1 & - & 7 & 2 & B_2 & \\
-315 & 5 & A_1 & + & 61 & 5 & A_2 & - & 20 & 1 & B_1 & - & 47 & 1 & B_2 & - & 13 & 1 & B_2 & \\
\frac{9 & 1 & B_2 & A_1 & - & 19 & 4 & B_2 & A_2 & - & 24 & 48 & B_2 & A_2 & \\
\end{bmatrix} \]

After further simplification equation (8) can be rewritten as:

\[ H_2 = \frac{p_1^2 + p_2^2}{2} + (p_1 q_2 - p_2 q_1) + e \cos f \left( \frac{q_1^2 + q_2^2}{2(1 + e \cos f)} \right) - \frac{1}{2(1 + e \cos f)} (H_{20} q_1^2 - H_{11} q_1 q_2 - H_{02} q_2^2) \]
\[ H_4 = \frac{-1}{24(1 + e \cos \theta)} \times (1 + 3(A_1 + A_2)/2) \times \]

\[
\left[ q_1^4 \times \right]
\]

\[
= \left\{ \frac{-111}{16} \left[ \frac{-1155A_1}{16} + \frac{9815}{16}A_2 + \frac{397\beta_1}{2} + \frac{25\beta_2}{2} \right] + \frac{1575}{16} \left[ \frac{395A_1}{16} + \frac{2945A_2}{16} + \frac{9269\beta_1}{16} \right] + \frac{495\beta_1}{32} + \frac{6755\beta_2A_1}{48} + \frac{60\beta_2A_2}{48} \right\}
\]

\[
\left[ +q_2^4 \times \right]
\]

\[
= \left\{ \frac{-75}{16} \left[ \frac{281A_1}{16} + \frac{21A_2}{16} + \frac{5\beta_1}{2} \right] + \frac{75}{8} \left[ \frac{5669A_1}{8} + \frac{117A_2}{8} + \frac{235\beta_1}{8} \right] + \frac{612\beta_1}{4} + \frac{2357\beta_2A_1}{156} + \frac{83\beta_2A_2}{48} \right\}
\]

\[
\left[ +\mu \times \right]
\]

\[
= \left\{ \frac{123}{16} \left[ \frac{4865A_1}{16} - \frac{105A_2}{8} + \frac{235\beta_1}{12} \right] + \frac{123}{8} \left[ \frac{5735A_1}{8} + \frac{1601A_2}{8} + \frac{42\beta_1}{8} \right] + \frac{31\beta_2}{4} \left[ \frac{4865\beta_2A_1}{16} + \frac{245\beta_2A_2}{32} \right] + \frac{45\beta_2A_1}{8} + \frac{539\beta_2A_2}{4} \right\}
\]

\[
\left[ +4\sqrt{3}q_1q_2 \times \right]
\]

\[
= \left\{ \frac{135}{16} \left[ \frac{1531A_1}{16} + \frac{15A_2}{4} - \frac{69\beta_1}{16} \right] + \frac{21\beta_2}{5} + \frac{23\beta_1A_2}{2} + \frac{15\beta_2A_2}{4} \right\}
\]

\[
\left[ +4\sqrt{3}q_1q_2^3 \times \right]
\]

\[
= \left\{ \frac{135}{8} \left[ \frac{337A_1}{2} - \frac{8097A_2}{12} + \frac{259\beta_1}{112} \right] + \frac{29\beta_1}{4} \left[ \frac{337A_1}{8} + \frac{139\beta_1A_1}{16} + \frac{1315\beta_2A_1}{32} + \frac{175\beta_2A_2}{116} \right] \right\}
\]

The characteristics equation can be written in following form as:

\[
\lambda^4 + (1 + e^2)\lambda^2 + \left( \frac{27\mu(1 - \mu)}{4} \right) \times \left[ 1 - 125 \frac{A_1}{6} + 40 \frac{A_2}{3} + \frac{5}{6}\beta_1 - \frac{35}{18}\beta_2 \right] = 0
\]

If \( \omega_1 \) and \( \omega_2 \) be the frequencies and putting \( \lambda^2 = -\omega^2 \) then

\[
\omega_1^2 = -\lambda_{1,2}^2
\]

\[
= \frac{1}{2} \left( 1 + e^2 \right) + \left( \frac{(1 + e^2)^2 - 27\mu(1 - \mu)}{4} \right)^{1/2}
\]

\[
\omega_2^2 = -\lambda_{3,4}^2
\]

\[
= \frac{1}{2} \left( 1 + e^2 \right) - \left( \frac{(1 + e^2)^2 - 27\mu(1 - \mu)}{4} \right)^{1/2}
\]

The correlation between \( \mu \) and \( \Omega_1 \) and \( \Omega_2 \) for \( A_1=0.0001, A_2=0.0002, \beta_1=0.001, \beta_2=0.002 \) is shown in figs. 1-5 for different values of radiation pressure and oblateness parameter. It is found that \( \omega_1 \) increases with increasing \( \mu \) whereas \( \omega_2 \) decreases, and becomes equal to the critical value which is shown in the figures.
4. Existence of resonance in elliptical cases

In order to discuss the existence of resonance we consider the following three cases:

case 1. When \(\omega_1 = \omega_2\)

\[\lambda_1^2 = \lambda_2^2, \quad \lambda_3^2 = 3,4\]

Solving we obtain:

\[
(1 + e^2)^2 - 2\mu(1 - \mu)(1 + e^2)\left(1 - \frac{125}{6}A_1 + \frac{40}{3}A_2 + \frac{5}{6}b_1 - \frac{35}{18}b_2\right) > 0
\]

For equality we have:

\[
\mu = \frac{1}{2}, \quad \text{the positive sign is inadmissible. Hence the region of stability in first approximation can be written as:}
\]

Thus, the value of \(\mu\) responsible for stable equilibrium points is given by:

\[
\mu_{\omega_1} = 0.0385208965 + 0.83601A_1 + 0.535048A_2 - 0.0334405b_1 + 0.0780279b_2 + e^4(0.01618 + 1.254A_1 - 0.80251A_2 - 0.50159 + 0.117023)\]

From equation (19) it is clear that, when \(A_1 = A_2 = \beta_1 = \beta_2 = 0\),

\[
\mu_c = 0.0385208965
\]

It is obvious that the case \(\omega_1 = \omega_2\) usually corresponds to a boundary of the region of stability of the system.

case 2. When \(\omega_1 = 2\omega_2\)

\[\lambda_1^2 = 4\lambda_2^2, \lambda_3^2 = 3,4\]

Solving for \(\mu\) the resonance value is obtained as:

\[
\mu_{\omega_2} = 0.0242939 + 0.519045A_1 + 0.33219A_2 + 0.20762b_1 - 0.0484445b_2 + e^4(0.19635 + 0.409165A_1 - 0.26185A_2 - 0.0163665b_1 + 0.0381885b_2)
\]

case 3. When \(\omega_1 = 3\omega_2\)

\[\lambda_1^2 = 9\lambda_2^2, \lambda_3^2 = 3,4\]

Solving for \(\mu\) the resonance value is obtained as:

\[
\mu_{\omega_3} = 0.0135160 + 0.2070A_1 - 12.9729A_2 - 0.8108b_1 + 3.7837b_2 + e^4(0.75 + 15.625A_1 - 10A_2 - 0.625b_1 + 1.45833b_2)
\]
5. Normalization and higher order stability of the libration points in non-resonance case

In order to investigate the stability the Hamiltonian $H$ is normalized by Birkhoff’s method to the following form:

$$
H = \varepsilon q_1 t - \varepsilon q_2 t^2 + c_20 q_1^2 + c_1 t \varepsilon t^2 + c_2 q_2^2 + c_3 q_1^2 t^2
$$

(21)

Where

$$
2l_i = p_i^2 + q_i^2, i = 1, 2
$$

$\varepsilon q_1, \varepsilon q_2$ are defined by equation (16).

It is well known fact that if $H_2$ is of a positive definite form, then the equilibrium position is stable by virtue of Liapunov theorem [28]. Otherwise the problem of stability is solved by KAM theorem as given by Arnold [29,30]. Considering the canonical transformation of variations given by [6]:

$$(q_1, q_2, p_1, p_2) = (q_1, q_2, p_1, p_2)N$$

(23)

where $N$ is defined as:

$$
N = \begin{bmatrix}
a_1 & a_p c_1 & -a_{c_1} & a_1 (1 - \varepsilon q_2 b_1) \\
a_2 & a_2 c_2 & -a_2 c_2 & a_2 (1 - \varepsilon q_2 b_2) \\
0 & a_1 b_1 & a_1 (1 - b_1) & a_1 c_1 \\
0 & -a_2 b_2 & -a_2 (1 - b_2) & -a_2 c_2
\end{bmatrix}
$$

(24)

where

$$
a_1 = -1 \left( \frac{2b_1}{2 \varepsilon q_1^2 - 1/2} \right)^{1/2}, a_2 = -1 \left( \frac{2b_2}{2 \varepsilon q_1^2 - 1/2} \right)^{1/2}
$$

$$
l_1 = 1 + \varepsilon q_2^2 + 2H_02, l_2 = 1 + \varepsilon q_2^2 + 2H_02
$$

$$
b_1 = \frac{2l_1}{l_1}; b_2 = \frac{2l_2}{l_2}; c_1 = -H_{11} l_1, c_2 = -H_{11} l_2
$$

(25)

The Hamiltonian $H$ defined in equation (7) is reduced to the following form by help of the transformation given by (23).

$$
H = \frac{1}{2} \left( p_1^2 + q_1^2 \right) - \frac{1}{2} \left( p_1^2 + q_1^2 \right) - \frac{1}{2} \left( p_2^2 + q_2^2 \right)
$$

$$
+ \sum_{\alpha + \gamma = 3} h_{\alpha, \alpha, \gamma, \gamma} q_1^\alpha q_2^\alpha p_1^\gamma p_2^\gamma
$$

where

$$
\alpha = a_1 + a_2; \gamma = 1 + \gamma 2
$$

The Hamiltonian $H_3$ and $H_4$ can be expanded as follows,

$$
H_3 = H_{0000}^3 p_3 + H_{0030}^3 p_3 + H_{0300}^3 p_3 + H_{0009}^3 p_3 + H_{2000}^3 q_2^2 + H_{2010}^3 q_1^2 p_1 + H_{2001}^3 p_1 p_2 + H_{2010}^3 q_1^2 p_1 + H_{2001}^3 p_1 p_2 + H_{0000}^4 q_1^4 p_1^4 + H_{0000}^4 q_1^4 p_1^4 + H_{0000}^4 q_1^4 p_1^4 + H_{0000}^4 q_1^4 p_1^4 + H_{1119}^4 q_1^4 p_1^4
$$

(26)

$$
H_4 = H_{0040}^4 p_4 + H_{0400}^4 p_4 + H_{0440}^4 p_4 + H_{4000}^4 p_4 + H_{4000}^4 p_4 + H_{4000}^4 p_4 + H_{4000}^4 p_4 + H_{4000}^4 p_4 + H_{4000}^4 p_4
$$

(27)

The coefficients of third and fourth terms of $h_{\alpha, \alpha, \gamma, \gamma}$, and $h_{\alpha, \alpha, \gamma, \gamma}$ are given in the appendices (1). For further investigation the Hamiltonian is reduced to a more convenient form, by the canonical transformation defined below as:

$$
q_1 = \frac{1}{2} q_1 + \frac{i}{\varepsilon q_1} q_1 p_1; p_1 = \frac{1}{2} i \varepsilon q_1^2 + q_1 p_1;
$$

$$
q_2 = -\frac{1}{2} q_2 + 2 \frac{i}{\varepsilon q_1} q_2 p_2; p_2 = -\frac{1}{2} i \varepsilon q_1^2 + q_2 p_2.
$$

(28)

Thus, the Hamiltonian (6) is reduced as:

$$
H = \varepsilon q_1 q_2 p_1 + i \varepsilon q_2 p_2 +
$$

$$
\sum_{\alpha + \gamma = 3} h_{\alpha, \alpha, \gamma, \gamma} q_1^\alpha q_2^\alpha p_1^\gamma p_2^\gamma,
$$

(29)

The other coefficients of third order terms are obtained by the formula and are given in appendices (2, 3).

$$
h_{\alpha, \alpha, \gamma, \gamma} = \left( i \alpha q_1 q_2 p_1 + i \alpha q_2 p_1 \right) \times \left( \frac{-\varepsilon q_1^2}{2} \right)^{\alpha, \gamma - \alpha}
$$

(30)

All the third order terms from the Hamiltonian (29) is nullified by using Birkhoff’s transformation $(q_1, p_1) \rightarrow (q_1, p_1)$. However, fourth order stabilization does not occur. This transformation is introduced by means of the generating function which is given as follows:

$$
\varepsilon = q_1 p_1 + q_2 p_2 + s_3 + s_4;
$$

(31)

Where

$$
q_i = q_i + \varepsilon q_i p_i + \varepsilon q_i p_i
$$

$$
p_i = p_i + \varepsilon q_i p_i + \varepsilon q_i p_i
$$

(32)

Using equation (29) and (32); expanding and equating the terms of the same degree on the two sides, we obtain:

$$
H_4(q_1, q_2; p_1, p_2) = H_2(q_1, q_2; p_1, p_2);
$$

$$
H_3(q_1, q_2; p_1, p_2) = \sum_{i=1}^{\infty} \left( \frac{\varepsilon q_i H_3}{\varepsilon q_i p_i} + \frac{\varepsilon q_i H_3}{\varepsilon q_i p_i} \right)
$$

$$
+ H_3(q_1, q_2; p_1, p_2);
$$

(33)

Where $K_4$ is the term other than the homogeneous ones in $q_1 p_1$ and $q_2 p_2$. By application of implicit function theorem, in equation (33) the new variables $q_1$ and $p_2$ can be replaced by $q_1^* and p_2^*$ on
both sides of equation (41). Considering autonomous system we have,
\[
\frac{\partial s_3}{\partial \alpha} = \frac{\partial s_4}{\partial \alpha} = 0.
\]
If we put
\[
H_3 = \sum_{\alpha+i\gamma=3}^{\infty} h_{\alpha,i\gamma,q_2^{\alpha},p_1^{\alpha},p_2^{\gamma}} t_i^\gamma,
\]
And
\[
s_3 = \sum_{\alpha+i\gamma=3}^{\infty} g_{\alpha,i\gamma,q_1^{\alpha},q_2^{\alpha},p_1^{\gamma},p_2^{\gamma}} t_i^\gamma,
\]
Equation (33) yields:
\[
g_{\alpha,i\gamma,q_1^{\alpha},q_2^{\alpha},p_1^{\gamma},p_2^{\gamma}} = \frac{\tilde{h}^{\alpha}}{(a_1 - a_2)01 + (a_2 - a_2)02}
\]
(35)
The new Hamiltonian inclusive of the fourth order terms can be found with help of equation (33) which is given as follows:
\[
H' = i\hbar q_1^{\alpha+1,2}q_2^{\alpha+1,2} - c_{20}(q_1^{\alpha+1,2}p_1^{\alpha+1,2})^2
+ c_{11}(q_1^{\alpha+1,2}q_2^{\alpha+1,2})p_1^{\alpha+1,2} - c_{21}(q_2^{\alpha+1,2}q_1^{\alpha+1,2})p_2^{\alpha+1,2} + ...
\]
(36)
Where
\[
K_4 = H_4(q_1^{\alpha+1,2}q_2^{\alpha+1,2}p_1^{\alpha+1,2} - \hbar^2 2020 q_1^{\alpha+1,2}p_1^{\alpha+1,2}
- \hbar^2 1111(q_1^{\alpha+1,2}q_2^{\alpha+1,2}) + \hbar^2 (q_2^{\alpha+1,2}q_1^{\alpha+1,2})^2;
\]
And c20, c11, c02 are given in appendixes.

Now we apply KAM- theorem which is stated as follows:
If the Hamiltonian of the perturbed motion is such that it satisfy the mentioned given conditions as:
1) If the characteristics equation of the system H2 has pure imaginary roots such that it holds the condition
\[
n_{i\gamma}q_1 + n_{20}q_2 = 0; \text{when} |n_1| + |n_2| \leq 4
\]
(n_j are integers)
2) \[
D = c_{20}q_1^2 + c_{11}q_1q_2 + c_{20}q_2^2 \neq 0
\]
If both the conditions are satisfied then the equilibrium points are stable.
The value of D is calculated with the help of following formula:
\[
D = c_{20}q_1^2 + c_{11}q_1q_2 + c_{20}q_2^2
\]
Fig 6-9 shows the values D for different values of radiation pressures and oblateness parameter. It is observed that D \neq 0, for any values of oblateness parameter. Hence, it is found that the equilibrium points are stable. Fig 10 shows the values of D for different values of eccentricity, taking oblateness parameter as fixed and by varying radiation parameter. Again, it is found that D \neq 0. Hence, the equilibrium points are stable.
6. Stability in the resonance case

Case 1: \( \omega_1 = 2 \omega_2 \)

In the resonance case \( \omega_1 = 2 \omega_2 \), the Birkhoffs transformation \( (Q_1^i, P_1^i) \rightarrow (Q_2^i, P_2^i) \) is used. It is not possible to cancel whole \( \bar{H} \) of the Hamiltonian \( H \). In this case \( \bar{H} \) retains two resonant terms with coefficients \( h_{002} \) and \( h_{021} \). Thus the Normalised form of the Hamiltonian is written as:

\[
\bar{H} = i (\omega_1 Q_1 P_1 + \omega_2 Q_2 P_2) + h_{002} Q_1 P_2^2 + h_{021} Q_2^2 P_1 + \ldots.
\]

For further investigation following two canonical transformation is used as:

\[
Q_1 = \frac{1}{(\omega_1)^{1/2}} (Q_1^0 - i P_1^0);
\]

\[
Q_2 = \frac{1}{(\omega_2)^{1/2}} (i Q_2^0 - P_2^0);
\]

\[
P_2 = \frac{(\omega_2)^{1/2}}{2} (i Q_2^0 - P_2^0);
\]

And

\[
Q_1^0 = (2 \eta_1)^{1/2} \sin(\phi_1 - \theta_1),
\]

\[
P_1^0 = (2 \eta_1)^{1/2} \cos(\phi_1 - \theta_1);
\]

\[
Q_2^0 = (2 \eta_2)^{1/2} \sin \phi_2
\]

\[
P_2^0 = (2 \eta_2)^{1/2} \cos \phi_2
\]

where

\[
\sin \theta_1 = \frac{y_{002}}{(x_{002}^2 + y_{002}^2)^{1/2}};
\]

\[
\cos \theta_2 = \frac{x_{002}}{(x_{002}^2 + y_{002}^2)^{1/2}}
\]

The Hamiltonian (29) is reduced to the following polar form as:

\[
\bar{H} = 2 \omega_1 \eta_1 - \omega_2 \beta_2 - \sqrt{{(x_{002}^2 + y_{002}^2)^2}} \sin(\eta_1 + \phi_2) + o((\eta_1 + \phi_2)^2)
\]

(41)

The nonlinear stability of the equilibrium points is determined by Markeev [31]. Accordingly, if \( D_1 = c_{22} + 2c_{11} + 4c_{02} \neq 0 \) and \( D_2 = (x_{002}^2 + y_{002}^2) = 0 \); hold simultaneously then the equilibrium points are stable otherwise unstable.

From Figs. 11-14, it is clear that for no values of the radiation pressure and oblateness parameter the expression \( D_1 \neq 0 \) and \( D_2 = 0 \) are true simultaneously. This clarify that the equilibrium points are unstable. Fig 15 depicts the value of \( D_1 \) and \( D_2 \) by considering oblateness parameter as constant and by varying the eccentricity. Hence, it follows that the motion is unstable in the resonance case \( \omega_1 = 2 \omega_2 \).
but by vary-

\[ \Phi = \rho - \theta \]

then the stability question is

\[ 3 \omega_3 \eta - c_2 \eta_2^2 + c_1 \eta_2 + c_2 \eta_2^2 + \]

\[ \frac{d \omega_2}{3} \times (3 + \eta_1 \eta_2 + \frac{1}{3} \eta_2^3) + \]

\[ \sin(q_1 + 3\eta_2) + \alpha(q_1 + \eta_2)^{3/2} \]

(45)

For sake of simplicity we denote

\[ a = c_20 + 3c_11 + 9c_2 \]

\[ d = 3c_22(\eta_1^2 + \eta_2^2) \]

(46) The stability problem can be resolved by application of the Mar-

keev theorem. According to:

1) \((x_1^{0003} + y_1^{0003}) \neq 0\) and \(d > |a|\) are simultaneously satisfied then the equilibrium points are unstable and if \(d < |a|\) then it is stable.

2) When \((x_1^{0003} + y_1^{0003}) = 0\) and \(d = 0\) are satisfied simultaneously then also, it is stable.

3) If \((x_1^{0003} + y_1^{0003}) = 0\) and \(d \neq 0\) then the stability question is decided by the analysis of higher order terms in the normal form.

From figs 16, 17 and 19 it is clear that, \((x_1^{0003} + y_1^{0003}) = 0\) and the condition \(d < |a|\) are satisfied, which states that the equilibrium points are stable. From Fig. 18 it is observed that for some combination of oblateness parameters and radiation parameters either \(d < |a|\) or \(d > |a|\). This states that for some cases it is stable and for some it is not stable. Fig 20 depicts the values of \(d\) and \(|a|\) by varying the eccentricity. Here, it is observed that \(d < |a|\), hence equilibrium points are stable.

The polar form of the normalized Hamiltonian reduces to the following form:

Fig 14: A1 VsD1, D2 for A2=0.0001, B1=0.001, B2 =0.002

Fig 15: "e" vs D1,D2 for A1=0.0001,A2=0.0002, B1=0.001, B2 =0.002.

Case (2) \(\Omega_1 = 3\Omega_2\).

In the resonance case \(\Omega_1 = 3\Omega_2\), it is possible to cancel whole of \(H_3\) of the Hamiltonian \(H\) but \(H_4\) retains the resonance terms and the terms with the same degree of canonical variables. Thus the normalized form of the Hamiltonian is written as:

\[ H = i(\eta_1 Q_1 + \eta_2 Q_2 - c_20 Q_1^2 + c_11 Q_1 Q_2 - c_22 Q_2^2 + h'1003 Q_1 P_2^3 + h'3010 Q_2 P_1^2 + \ldots) \]

(42)

Again, applying the canonical transformation by means of polar coordinates given as:

\[ Q_1 = (2\pi)^{1/2} \sin(q_1 - \theta_1) \]

\[ P_1 = (2\pi)^{1/2} \cos(q_1 - \theta_1); \quad (i = 1, 2) \]

(43)

Where

\[ \theta_2 = 0 \]

\[ \sin \theta_1 = \frac{\eta_1^{0003}}{(x_1^{0003} + y_1^{0003})^{1/2}} \]

\[ \cos \theta_1 = \frac{\eta_2^{0003}}{(x_1^{0003} + y_1^{0003})^{1/2}} \]

(44)

Fig 16: A2 vs 'a' and 'd' for A1=0.0001, B1=0.001, B2 =0.001.
7. Discussion and conclusion

The stability of the triangular equilibrium points in ER3BP is investigated considering both the primaries are radiating and oblate; under both non-resonance and resonance case. Recently [32] studied nonlinear stability of the triangular points considering both the primaries as radiating in ER3BP in non-resonance case. It was found that the exception for some values of radiation pressure the triangular points are stable. The resonance condition was also studied by [33] considering only radiating primaries and observed that the motion is stable for third order resonence but unstable for fourth order resonance. [34] Studied the nonlinear stability in CR3BP taking radiating and oblate primaries in resonance case. It was observed that in resonance cases \( \omega_1 = 2\omega_2 \) the motion is unstable while for \( \omega_1 = 3\omega_2 \), motion is stable for all values of radiation pressures taken. [35] studied the nonlinear stability in CR3BP in non-resonance case considering both the primaries as oblate luminous spheroid and found that except few cases considered, the triangular points are stable. It was observed that in general the stability character remains same even if oblateness factor is considered apart from radiation factor in circular cases.

The following observation has been made regarding the nonlinear stability in both resonance as well as non-resonance case considering the luminous oblate spheroid in ER3BP.

It is found that \( \omega_1 = \omega_2 \) corresponds to the boundary region of the stability for the system, whereas the other two cases \( \omega_1 = 2\omega_2, \omega_1 = 3\omega_2 \) correspond to the resonant cases.

It is noticed that \( \omega_1 \) increases with increasing \( \mu \) whereas \( \omega_2 \) decreases, and becomes equal to the critical value (i.e. \( \mu = \mu_c \)). In non-resonance case, there in no cases where \( D = 0 \). Hence it is found that the equilibrium points are stable.

In resonance case \( \omega_1 = 2\omega_2 \), it is clear from Fig 11-15 that in no case \( D_1 = 0 \) and \( D_2 = 0 \) holds simultaneously true. Hence it follows that the motion is unstable.

In resonance case \( \omega_1 = 3\omega_2 \), for some cases it is stable and for some it is unstable.

References


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