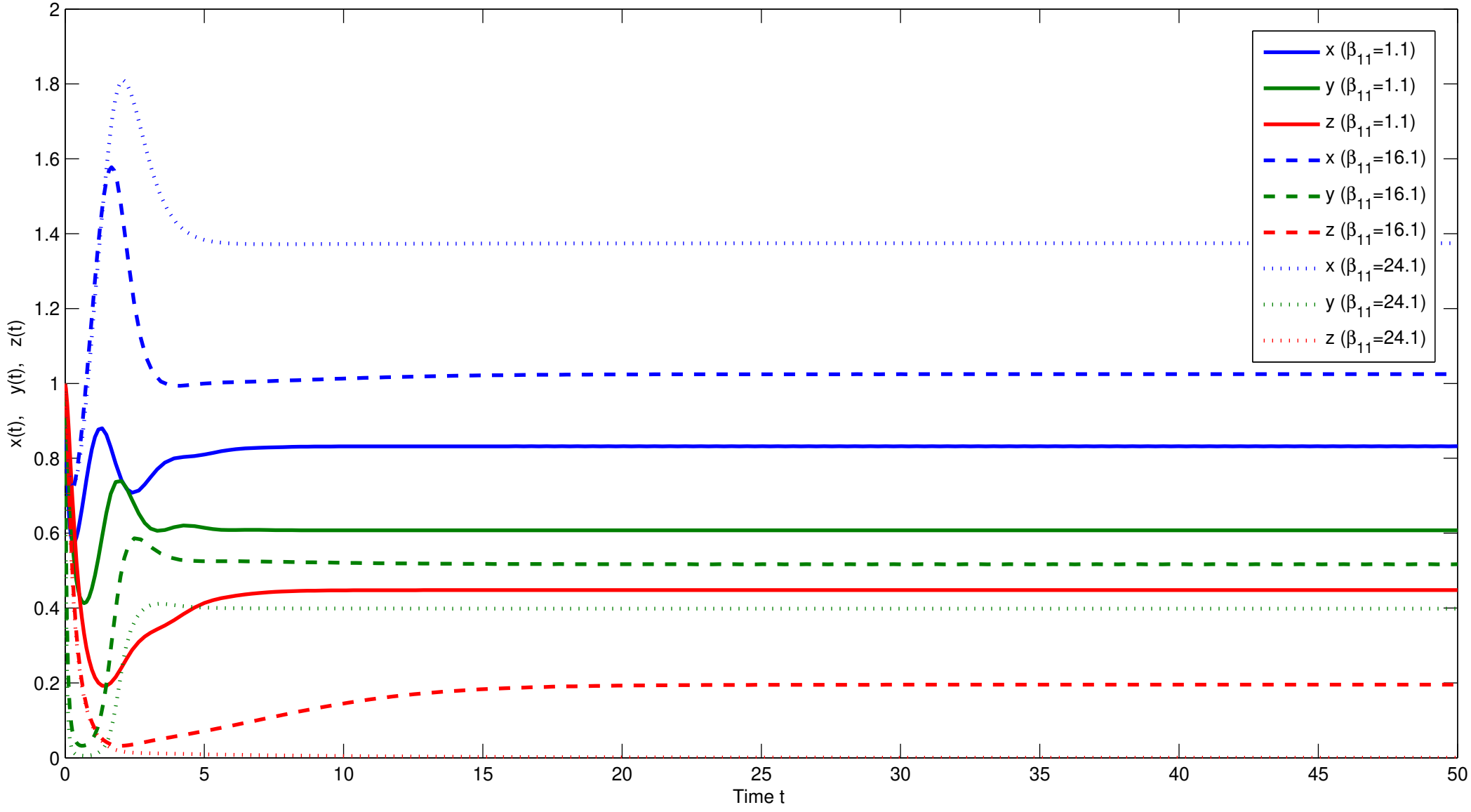
x (β11=1.1)
y (β11=1.1)
z (β11=1.1)
x (β11=16.1)
y (β11=16.1)
z (β11=16.1)
x (β11=24.1)
y (β11=24.1)
z (β11=24.1)
x(t), y(t), z(t)
Time t
0
0.2
0.4
0.6
0.8
1
1.2
1.4
1.6
1.8
2
0
5
10
15
20
25
30
35
40
45
50